AE/PHE/EE/II/24



- 1. Floating battery systems are widely used for
- (A) power station
 - (B) emergency lighting
 - (C) telephone exchange installation
 - (D) All of the above
 - adiant fier
- **2.** The Thevenin voltage and resistance of the given circuit seen from terminals *a* and *b* are



(B) 4 V and 1 Ω

- (C) $\frac{1}{2}$ V and 1 Ω
- (D) 1 V and 2 Ω
- **3.** In the given circuit, the value of V is equal to



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- 4. The Thevenin equivalent of a circuit operating at $\omega = 5$ rad/s has
 - $V_{\rm oc} = 3 \cdot 7 \angle -15 \cdot 9^{\circ} V$ $Z_0 = 2 \cdot 8 + j 0 \cdot 67 \Omega$
 - At this frequency, the minimal realization of the Thevenin impedance will have
 - (A) a resistor, a capacitor and an inductor
 - (B) a resistor and a capacitor
 - (C) a resistor and an inductor

(D) a capacitor and an inductor

- Answer-Sheet without marking Series shell and he contracted
- 5. A complex current wave is given by $i = 5 + 5 \sin 100\pi t$ A. The average value will be
 - (A) 10 A (B) 0 A (C) $\sqrt{50}$ A (D) 5 A
- 6. A resistance of 5 Ω is connected in a branch of a network. The current in this branch is 2 A. If this 5 Ω resistor is replaced by a 10 Ω resistor, the current in the branch
 - (A) may be more or less than 2 A
 - (B) will be more than 2 A
 - (C) will be less than 2 A
 - (D) will be 2 A
- Two incandescent lightbulbs of 40 W and 60 W rating are connected in series across the mains. Then
 - (A) the bulbs together consume 100 W
 - (B) the bulbs together consume 50 W
 - (C) the 60 W bulb glows brighter
 - (D) the 40 W bulb glows brighter

R. : There will be acgutiv

- 8. A practical current source is usually represented by
 - (A) a resistance in series with an ideal current source
 - (B) a resistance in parallel with an ideal current source
- (C) a resistance in parallel with an ideal voltage source
 - (D) None of the above
 - **9.** A dead storage battery can be revived by
 - (A) a dose of H_2SO_4
 - (B) adding so-called battery restorer
 - (C) adding distilled water
 - (D) None of the above
 - **10.** In the given circuit, the initial capacitor voltage is zero. The switch is closed at t = 0. The final steady-state voltage across the capacitor is



- 11. A circuit with resistor, inductor and capacitor in series is resonant at f_0 Hz. If all the component values are now halved, the new resonant frequency is
 - (A) $2f_0$ Hz
 - (B) still f_0 Hz
 - (C) $(f_0 / 4)$ Hz
 - (D) $(f_0 / 2)$ Hz
- **12.** In the given circuit, ammeter A_2 reads 4 A and A_3 reads 3 A. Then A_1



13. Given two coupled inductors L_1 and L_2 , their mutual inductance M satisfies

- (A) $M = \sqrt{L_1^2 + L_2^2}$
- (B) $M > \frac{L_1 + L_2}{2}$ (6)
- (C) $M > \sqrt{L_1 L_2}$ and the (D)
- (D) $M \leq \sqrt{L_1 L_2}$

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14. The electric field strength between two charges -5Q and +2Q separated by 50 cm is zero

- (A) at midway between them
- (B) at perpendicular bisector
- (C) beyond the positive charge
- (D) beyond the negative charge
- **15.** Identify the Maxwell's equation from the following.
 - (A) $\nabla \cdot \vec{D} = \rho_v$
 - (B) $\nabla \times \vec{E} = 0$
 - (C) $\oint \vec{E} \cdot d\vec{l} = 0$
 - (D) All of the above
- 16. A single-phase diode bridge rectifier supplies a highly inductive load. The load current can be assumed to be ripple free. The a.c. supply side current waveform will be
 - (A) sinusoidal
 - (B) constant d.c.
 - (C) square
 - (D) triangular

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- **17.** Which of the following statements holds true for divergence of electric and magnetic flux densities?
 - (A) Both are zero.
- (B) They are zero for static densities but non-zero for time-varying densities.
 - (C) It is zero for the electric flux density.
 - (D) It is zero for the magnetic flux density.
- **18.** In a uniform electric field, the field lines at equipotential surfaces
 - (A) are parallel to one another
 - (B) intersect at 45°
 - (C) intersect at 30° be (C)
 - (D) are orthogonal
- **19.** If \vec{E} is the electric field intensity, then $\nabla \cdot (\nabla \times \vec{E})$ is equal to
 - (A) \vec{E}
 - (B) $|\vec{E}| = 200$
 - a sea a ser a ser a ser a vala VV---
 - (C) null vector
 - (D) zero
- **20.** A dynamometer-type wattmeter responds to the
 - (A) average value of active power
 - (B) average value of reactive power
 - (C) peak value of active power
 - (D) peak value of reactive power
- 4

- 21. The two-wattmeter method is used to measure active power on a 3-phase, 3-wire system. If the phase voltage is unbalanced, then the power reading is
 - (A) affected by both negative sequence and zero sequence voltages
 - (B) affected by negative sequence voltage but not by zero sequence voltage
 - (C) affected by zero sequence voltage but not by negative sequence voltage
 - (D) not affected by negative or zero sequence voltage
- 22. A pressure gauge is calibrated from $0-50 \text{ kN/m}^2$. It has a uniform scale with 100 scale divisions. One-fifth of the scale divisions can be read with certainty. The gauge has
 - (A) resolution of 0.1 kN/m^2
 - (B) threshold of 0.1 kN/m²
 - (C) dead zone of 0.2 kN/m^2
 - (D) resolution of 0.5 kN/m^2
- 23. A Wheatstone bridge is balanced with all the four resistances equal to $1 k\Omega$ each. The bridge supply voltage is 100 V. The value of one of the resistances is changed to 1010Ω . The output voltage is measured with a voltage-measuring device of infinite resistance. The bridge sensitivity is
 - (A) 10 V/Ω
 - (B) 2·5 mV/Ω
 - (C) $25 \text{ mV}/\Omega$
 - (D) None of the above

- 24. A moving-coil instrument gives a full-scale deflection with a current of $40 \mu A$, while the internal resistance of the meter is 500Ω . It is to be used as a voltmeter to measure a voltage range of 0–10 V. The multiplier resistance needed is equal to
 - (A) 2498·5 kΩ
 - (B) 2400 kΩ
 - (C) 500 kΩ
 - A = A
 - (D) 1000 kΩ
- 25. The current passing through a 10 Ω resistor is given by
 - $i = 3 + 4\sqrt{2} \sin 314t$ A

This current is measured by a PMMC meter. The measured value is

rescondition () and (c)

(A) 3 A solution () 90 (O)

(B) 5 Apzelq Hilm 1.8 (0)

(C) 4 A branco el 202 nA .00 (D) $4\sqrt{2}$ A

(A) it can be turned OFF but not

26. In 2's complement representation, the number 11100101 represents the decimal number

- (A) +31
- a' 40, berrut, ed. (ts) ii. (0) (B) -31 s; s (brw PHO
- (C) +27 of the transformed (C)

(D) -27 lov guitaments

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27. For the minterm designation $Y = \sum m(1, 3, 5, 7)$, the complete expression is

(A) $Y = \overline{A} \overline{B}C + \overline{A}BC$

(B) $Y = \overline{A}\overline{B}C + \overline{A}BC + A\overline{B}C + ABC$

- (C) $Y = \overline{A}\overline{B}\overline{C} + \overline{A}\overline{B}C + \overline{A}BC + \overline{A}BC$
 - (D) $Y = \overline{A}\overline{B}\overline{C} + ABC + \overline{A}\overline{B}C + A\overline{B}C$
- 28. De Morgan's second theorem is
 - (A) $A \cdot \overline{A} = 0$
 - (B) $\overline{\overline{A}} = A$
 - (C) $\overline{A+B} = \overline{A} \cdot \overline{B}$
 - (D) $\overline{AB} = \overline{A} + \overline{B}$
- 29. Two 16:1 multiplexers and one2:1 multiplexer can be connected to form a/an
 - (A) 16:1 multiplexer
 - (B) 32:1 multiplexer
 - (C) 64 : 1 multiplexer
 - (D) 8:1 multiplexer
- **30.** An SCR is considered to be a semi-controlled device because
 - (A) it can be turned OFF but not ON with a gate pulse
 - (B) it conducts only during one half cycle of an alternating current wave
 - (C) it can be turned ON but not OFF with a gate pulse
 - (D) it can be turned ON only during one half cycle of an alternating voltage wave

6

AE/PHE/EE/II/24/36-A

- **31.** The bridge method commonly used for finding mutual inductance is
 - (A) Heaviside-Campbell bridge
 - (B) Schering bridge
 - (C) De Sauty bridge
 - (D) Wien bridge
- **32.** The typical ratio of holding current to latching current in a 20 A thyristor
 - (A) 5

is

- (B) 2
- (-) -
- (C) 1
- (D) 0·5
- 33. A 3-phase full converter operates at 50 Hz. The ripple frequency in the output voltage is
 - (A) 50 Hz
 - (B) 100 Hz
 - (C) 150 Hz
 - (D) 300 Hz



$$F(s) = \frac{5}{s(s^2 + 3s + 2)}$$

where F(s) is the Laplace transform of the function f(t). The initial value of f(t) is equal to

| (A) | 5 | |
|-----|-----|----------------------------------|
| (B) | 5/2 | $\Omega \setminus V $ $OI = (A)$ |
| (C) | 5/3 | |
| (D) | 0 | |

35. The characteristic equation of a system is given by

$$3s^4 + 10s^3 + 5s^2 + 2 = 0$$

- This system is
- (A) unstable
- (B) marginally stable
- (C) stable
- (D) linear
- 36. Signal flow graph is used to obtain
 - (A) the stability of a system
 - (B) the controllability of a system
 - (C) both stability and controllability of a system
 - (D) the transfer function of a system
- **37.** The principles of homogeneity and superposition are applied to
 - (A) linear time-invariant systems
 - (B) non-linear time-invariant systems
 - (C) linear time-variant systems
 - (D) non-linear time-variant

systems

- **38.** A boost converter is operated in the continuous conduction mode in steady state with a constant duty ratio D. If V_o is the magnitude of the DC output voltage and V_s is the magnitude of the DC input voltage, then the ratio V_o / V_s is given by
 - (A) D
 - (B) $\frac{1}{D}$
 - (C) $\frac{1}{1}$

(C)
$$\frac{1}{1-D}$$

(D)
$$\frac{1}{1-D}$$

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39. If the loop gain K of a negative feedback system having a loop transfer function

$$\frac{K(s+3)}{(s+8)^2}$$

is to be adjusted to induce a sustained oscillation, then

- (A) the frequency of this oscillation must be $\frac{4}{\sqrt{3}}$ rad/s
- (B) the frequency of this oscillation must be 4 rad/s
- (C) the frequency of this oscillation must be 4 or $\frac{4}{\sqrt{3}}$ rad/s
- (D) such K does not exist
- **40.** Consider the signal flow graph shown in the given figure :



The
$$C(s) / R(s)$$
 will be

(A)
$$\frac{G_1 G_2 G_3}{1 - G_1 G_2 H_1 + G_2 G_3 H_2 + G_1 G_2 G_3}$$

(B)
$$\frac{G_1G_2G_3}{1+G_1G_2H_1+G_2G_3H_2+G_1G_2G_3}$$

(C)
$$\frac{G_1G_2G_3}{1 - G_1G_2H_1 - G_2G_3H_2 - G_1G_2G_3}$$

(D) None of the above

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41. The Laplace transformation of the function

 $f(t) = \frac{A}{t_0}; \text{ for } 0 < t < t_0$ = 0; for t < 0, t_0 < t

is (A) $\frac{1}{s}(1-e^{-st_0})$

anal to formation and

(B) $\frac{A}{t_0 s} (1 - e^{-st_0})$

(C)
$$\frac{A}{t_0}(1-e^{-st_0A})$$

(D)
$$\frac{1}{t_0}(1-e^{-t_0A})$$

ng woli .

- 42. Two in-phase 50 Hz sinusoidal waveforms of unit amplitude are fed into channel-1 and channel-2 respectively of an oscilloscope. Assuming that the voltage scale, time scale and other settings are exactly the same for both the channels, what would be observed if the oscilloscope is operated in x-ymode?
 - (A) A circle of unit radius

(B) An ellipse

- (C) A parabola
- (D) A straight line inclined at 45° with respect to the x-axis

AE/PHE/EE/II/24/36-A

- **43.** A bulb in a staircase has two switches, one switch being on the ground floor and the other one at first floor. The bulb can be turned ON and also can be turned OFF by any one of the switches irrespective of the state of the other switch. The logic of switching of the bulb resembles
 - (A) an AND gate
 - we wood of them in the
 - (B) an OR gate
 - (C) an XOR gate
 - (D) a NAND gate
- **44.** A cascade of three identical modulo-5 counters has an overall modulus of
 - m (A) 5 mm month and 10
 - 8
 - (B) 25
 - (C) 125
 - (D) 625
 - continuous conduction mo
- **45.** Thyristor circuits that directly convert polyphase AC voltage from one frequency to another frequency are called
 - (A) regulator
 - (B) converter
 - (C) bidirectional converter
 - (D) cycloconverter

46. In the given transistor circuit, the collector to ground voltage is +20 V. Which of the following is the probable cause of error?



- (A) Collector-emitter a terminals shorted and book
- (B) Emitter to ground connection open
 - (C) $10 \text{ k}\Omega$ resistor open
 - V BN
 - (D) Collector-base terminals shorted

(D) 50 1

So. In frequency modulation

47. The complete set of only those logic gates designated as universal gates is

(B) carrier frequency is changed by

(A) NOT and NAND gates

(B) XNOR, NOR and NAND gates

(C) NOT, OR and AND gates

(D) XOR, NOR and NAND gates

AE/PHE/EE/II/24/36-A

48. The nature of feedback in the OPAMP circuit shown below is



- (A) voltage-voltage feedback
- (B) voltage-current feedback
- (C) current-current feedback
- (D) current-voltage feedback

49. In forward voltage triggering, thyristor

- (A) changes from OFF state to ON state
 - (B) inverts the state
 - (C) changes from ON state to OFF state
 - (D) state remains the same
- **50.** In a thyristor converter, a freewheeling diode is used to
 - (A) add to the conduction current of the thyristor
 - (B) oppose the thyristor conduc-
- (C) conduct current during the OFF period of the thyristor
 - (D) protect the thyristor by providing a shunt path

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- 51. A DC chopper has a resistive load of 10Ω and an input voltage of 220 V. When the chopper is ON, its voltage drop is 2 V and the chopping frequency is 1 kHz. If the duty cycle is 50%, the average output voltage will be
 - (A) 100 V
 - (B) 103 V
 - (C) 106 V
 - (D) 109 V

52. A step-up chopper has input voltage of 100 V and output voltage of 300 V. If the non-conducting time of thyristor chopper is 100 μ s, the pulse width of the output voltage is

(A) 200 µs

- (B) 100 μs
- (C) 300 µs
- (D) 50 μs
- -
- 53. A clamping circuit
 - (A) adds a DC component to an AC signal either side
 - (B) adds an AC component to a DC signal either side
 - (C) adds a DC component to an AC signal in positive direction
 - (D) None of the above

AE/PHE/EE/II/24/36-A

- **54.** Which of the following devices can be considered as a clipping circuit?
 - (A) Full-wave converter
 - (B) Half-wave rectifier
 - (C) Bridge rectifier with a smoothing capacitor
 - (D) Common-base configuration of a BJT

55. A half-wave rectifier with silicon diode produces (peak) maximum load current of 50 mA through a 1200Ω resistor. If the voltage drop across the diode is 0.7 V, the PIV of the diode will be

- (A) 48.7 V
- (B) 48 V
- (C) 24 V
 - (D) 50 V

56. In frequency modulation

- (A) carrier amplitude is changed by the modulating signal
 - (B) carrier frequency is changed by the modulating signal
 - (C) if amplitude of modulating signal increases, the carrier frequency remains constant
 - (D) frequency of the carrier must be lower than the modulating frequency

57. In the feedback network of the given figure, if the feedback factor k is increased, then



- (A) input impedance increases and output impedance decreases
- (B) both input and output impedances increase
- and output (C) both input impedances decrease
- (D) input impedance decreases and output impedance increases
- 58. Which of the following is a result of over-modulation?
 - (A) Weakening of signal
- (B) Distortion
 - (C) Strengthening of signal
 - (D) Excessive carrier power
 - **59.** For the equation

 $\ddot{x}(t) + 3\dot{x}(t) + 2x(t) = 5$

the solution x(t) approaches which of the following values as $t \to \infty$?

- (A) 0
- (B) 5/2
- (C) 5
- (D) 10

AE/PHE/EE/II/24/36-A

60. A digital-to-analog converter with a full-scale output voltage of 3.5 V has a resolution close to 14 mV. Its bit size is

> (A) 4 (B) 8 (C) 16 (D) 32

61. List-I lists different appliances and List-II lists motors for these appliances. Match the appliance with the most suitable motor and right combination the choose among the choices given :

- List-II List-I 1. Permanent a. Food mixer magnet DC motor 2. Single-phase Cassette tape b. induction motor recorder 3. Universal motor c. Domestic water pump 4. Three-phase d. Escalator
 - induction motor
 - 5. DC series motor
 - 6. Stepper motor

Codes :

| (A) | a | b | С | d | P. A P.C. |
|-----|---|---|------|---|-----------|
| von | 3 | 6 | 4 | 5 | |
| (B) | a | b | с | d | |
| | 1 | 3 | 2 | 4 | |
| (C) | а | b | с | d | |
| | 3 | 1 | 2 | 4 | |
| (D) | а | b | с | d | |
| | 3 | 2 | 1214 | 4 | |
| | | | | | |

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- 62. A 4-pole lap-wound DC generator has a developed power of P watts and a voltage of E volts. Two adjacent brushes of the machine are removed as they are worn out. If the machine operates with the remaining brushes, the developed voltage and power that can be obtained from the machine are
 - (A) $\frac{E}{2}$ volts and $\frac{P}{2}$ watts (B) E volts and $\frac{P}{2}$ watts
 - (C) E volts and $\frac{P}{4}$ watts
 - (D) E volts and P watts
- **63.** A DC machine is connected to 220 V supply mains. Its armature resistance is 0.2Ω . The magnitude of e.m.f. generated so that it may feed 100 A to supply is
 - (A) 200 V
 - (B) 220 V
 - (C) 240 V
 - (D) 260 V
- **64.** A 4-pole, 50 Hz, 400 V, three-phase induction motor is running at 1440 r.p.m. The frequency of the rotor induced e.m.f. is
 - (A) 2 Hz
 - (B) 4 Hz
 - (C) 1 Hz
 - (D) 50 Hz

- **65.** The core loss and copper loss of a transformer on full load are 400 W and 600 W respectively. Their values at one-third of full load will be
 - (A) 133.3 W and 200 W
 - (B) 400 W and 66.66 W
 - (C) 133.3 W and 600 W

(D) 400 W and 200 W

66. A 5 kVA, 1000/200 V, 50 Hz, singlephase transformer has the following no-load and short-circuit test data :

No-load test : $W_0 = 90$ W, $I_0 = 1.2$ A, V = 200 V Shortcircuit test : $W_{sc} = 110$ W, $I_{sc} = 5$ A $V_{sc} = 50$ V

The full-load copper loss and iron loss will be

[1] Breek, en camer i nov.

(A) 90 W and 110 W

(B) 110 W and 100 W

- (C) 110 W and 90 W
- (D) 90 W and 90 W

67. Cogging and crawling are phenomena associated with

> (A) cage induction machines and they are essentially the same

(B) squirrel-cage induction machines, the former at a fraction of its rated speed and the latter during starting

> (C) squirrel-cage induction machines, the former during starting and the latter at a fraction of its rated speed

(D) wound-rotor induction machines and they are reduced by skewing, chording and distribution of windings

68. A large capacity 3-phase induction motor is started using a star-delta starter instead of DOL starter. The current

(A) is increased three times

(B) remains constant

(C) is reduced to one-third of its value

(D) is reduced to half of its value

AE/PHE/EE/II/24/36-A

69. The e.m.f. induced in the armature of a DC generator is alternating in nature but in the output circuit, DC is made available by

(A) brush and slip-ring arrangement

- (B) brush and commutator arrangement
- (C) diode rectifiers
- at normal excitation, th
- (D) converter circuit
- **70.** For synchronizing an alternator with the bus bar, which of the following conditions is *not* applicable?
 - e Supplyanter to
- (A) The generated voltage of the alternator should be equal to the bus bar voltage

Compensating winding is

(B) The frequency of the generated voltage should be equal to the bus bar frequency

(C) The phase sequence of the voltage generated should be the same as that of the bus bar voltage

(D) The kVA rating of the alternator should be equal to the kVA rating of the other alternators already connected to the bus bar

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- **71.** Which of the following statements is *not* true for a synchronous motor?
 - (A) An over-excited synchronous motor draws lagging power factor.
 - (B) An over-excited synchronous motor draws leading power factor.
 - (C) At normal excitation, the current drawn by a synchronous motor is the minimum.
 - (D) At normal excitation, the power factor of the current drawn is unity.
 - **72.** In a DC machine, which of the following statements is true?
 - (A) Compensating winding is used for neutralizing armature reaction while inter-pole winding is used for producing residual flux.
- (B) Compensating winding is used for neutralizing armature reaction while inter-pole winding is used for improving commutation.
- (C) Compensating winding is used for improving commutation while inter-pole winding is used for neutralizing armature reaction.
 - (D) Compensating winding is used for improving commutation while inter-pole winding is used for producing residual flux.

- **73.** In a split-phase capacitor-start induction motor, a time phase difference between the currents flowing through the two windings of the stator is produced by
 - (A) placing the two windings at an angle of 90° in the stator slots
 - (B) applying two-phase supply across the two windings
 - (C) introducing capacitive reactance in the auxiliary winding circuit
 - (D) connecting the two windings in series opposition across a single-phase supply

74. It is desirable to eliminate 5th harmonic voltage from the phase voltage of an alternator. The coils should be short pitched by an electrical angle of

- (A) 30°
- (B) 36°
- (C) 72° besimi and
 - (0.571)
- (D) 18°
- **75.** A four-point starter is used to start and control the speed of a
 - (A) DC shunt motor with armature resistance control
 - (B) DC shunt motor with field weakening control
 - (C) DC series motor
 - (D) DC compound motor

76. The r.m.s. value of a half-wave rectified symmetrical square-wave voltage of 2 V is

- (A) √2 V
- (B) 1 V
- (C) $\frac{1}{\sqrt{2}}$ V
- (D) √3 V
- **77.** The rated voltage of a 3-phase power system is given as
 - sertes inductive comp
 - (A) r.m.s. phase voltage
 - (B) peak phase voltage
- (C) r.m.s. line-to-line voltage
 - (D) peak line-to-line voltage

at the scuding and

78. Consider a long, two-wire line composed of solid round conductors. The radius of both the conductors is 0.25 cm and the distance between their centres is 1 m. If this distance is doubled, then the inductance per unit length

(A) doubles

- EDIS BOTISTON
- (C) increases but does not double
 - (D) decreases but does not halve

15

AE/PHE/EE/II/24**/36-A**

79. If the fault current is 2000 A, the relay setting is 50% and CT ratio is $\frac{400}{5}$, then the plug setting multiplier will be

(A) 25 (A)

(B) 15

(C) 50

1

(D) 10 paters in ju

80. The relay that has capability of anticipating the possible major fault in a transformer is

- (A) over-current relay
 - (B) differential relay
 - (C) Buchholz relay
 - (D) None of the above
- **81.** The per unit impedance of a circuit element is 0.30. If the base kV and base MVA are halved, then the new value of the per unit impedance of the circuit element will be
 - (A) 0·30
 - (B) 0.60 complements (8)
 - (C) 0.0030
 - (D) 0.0060 and and a (3)

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82. The transient stability of a power system can be effectively improved by

- (A) excitation improvement
- (B) phase-shifting transformer
- (C) single-pole switching of circuit breakers
- (D) increasing the turbine valve opening
- 83. A lightning stroke discharges an impulse current of 10 kA (peak) on a 400 kV transmission line having surge impedance of 250 Ω . The magnitude of transient over-voltage travelling waves in either direction assuming equal distribution from the point of lightning strike will be
 - (A) 1250 kV
 - (B) 1650 kV
 - (C) 2500 kV
 - (D) 2900 kV
- **84.** A negative sequence relay is commonly used to protect
 - (A) an alternator
 - (B) a transformer
 - (C) a transmission line
 - (D) a bus bar

AE/PHE/EE/II/24/36-A

- **85.** To avoid maloperation of differential protection of transformers connected in Δ -Y mode, the CT must be connected in
 - (A) $Y-\Delta$ mode
 - (B) Y-Y mode
 - (C) Δ -Y mode
 - (D) Δ - Δ mode
- **86.** For enhancing the power transmission in a long EHV transmission line, the most preferred method is to connect a
 - (A) series inductive compensator in the line
 - (B) shunt inductive compensator at the receiving end
 - (C) series capacitive compensator in the line
 - (D) shunt capacitive compensator at the sending end
- 87. The angle δ in the swing equation of a synchronous generator is the
 - (A) angle between stator voltage and current
 - (B) angular displacement of the rotor with respect to the stator
 - (C) angular displacement of an axis fixed to the rotor with respect to a synchronously rotating axis
 - (D) angular displacement of the stator m.m.f. with respect to a synchronously rotating axis

88. For load flow solutions, the quantities specified at load bus are

- (A) P and |V|
- (B) P and Q
- (C) P and δ
- (D) Q and |V|
- **89.** In Gauss-Seidel method of power flow problem, the number of iterations may be reduced if the correction in voltage at each bus is multiplied by
 - (A) Gauss constant
 - (B) acceleration constant
 - (C) blocking factor
 - (D) deceleration constant

90. For a Y-bus matrix of a 4-bus system given in per unit, the buses having shunt elements are

 $Y_{\text{bus}} = j \begin{bmatrix} -5 & 2 & 2 \cdot 5 & 0 \\ 2 & -10 & 2 \cdot 5 & 4 \\ 2 \cdot 5 & 2 \cdot 5 & -9 & 4 \\ 0 & 4 & 4 & -8 \end{bmatrix}$

(A) 3 and 4

(B) 2 and 3

- (C) 1 and 2
- (D) 1, 2 and 4

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- **91.** In a two-plant system, the load is connected to plant 2. Then
 - (A) loss coefficients B_{11} , B_{12} and B_{22} are zero
 - (B) loss coefficient B_{11} is non-zero but B_{12} and B_{22} are zero
 - (C) loss coefficients B_{11} and B_{12} are non-zero but B_{22} is zero
 - (D) loss coefficients B_{11} and B_{22} are non-zero but B_{12} is zero
- **92.** Normally Z_{bus} matrix of a power system is a
 - (A) null matrix
 - (B) sparse matrix
 - (C) full matrix
 - (D) unity matrix
- **93.** A water boiler at home is switched on to the AC mains supplying power at 230 V/50 Hz. The frequency of instantaneous power consumed by the boiler is
 - (A) 0 Hz
 - (B) 50 Hz
 - (C) 100 Hz
 - (D) 150 Hz
- **94.** The powers generated by two plants are $P_1 = 50$ MW and $P_2 = 40$ MW. If the loss coefficients are

$$B_{11} = 0.001, B_{22} = 0.0025$$

 $B_{12} = -0.0005$

- then the power loss will be
- (A) 5.5 MW
- (B) 4.5 MW
- (C) 6·5 MW
- (D) 8.5 MW

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- **95.** Economic operation of power system is carried out on the basis of
 - (A) equal incremental fuel cost
 - (B) equal area criterion
- (C) equal fuel cost
- (D) all units sharing equal power
- **96.** The knowledge of maximum sag is essential in determining the
 - (A) ground clearance of the conductor
 - (B) maximum span of the conductor
 - (C) maximum stress of the conductor
 - (D) None of the above

97. The term 'self-GMD' is used to calculate

- (A) capacitance
 - (B) inductance
 - (C) Both (A) and (B)
 - 6-5 MW
 - (D) resistance

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- **98.** A large size synchronous generator is protected against overloads by
 - (A) over-current relay
 - (B) mho relay bas a (8)
 - (C) temperature-sensitive relay
 - (D) Buchholz relay
- **99.** In central AGC (Automatic Generation Control) of a given control area, the change (error) in frequency is
 - (A) area control error
 - (B) volume control error
 - (C) non-linear control error
 - (D) optimal control error
- **100.** The receiving-end voltage for a long transmission line under no-load condition is
 - (A) less than the sending-end voltage
 - (B) more than the sending-end voltage
 - (C) equal to the sending-end voltage
 - (D) None of the above

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